T. Jabeen (Abdus Salam School Math. Sci., GC Univ., Lahore, Pakistan),

R. P. Agarwal (Texas A&M University-Kingvsille, Kingsville, USA),

V. Lupulescu (Constantin Brancusi Univ., Targu-Jiu, Romania),

D. O'Regan (School Math., Statistics and Appl. Math., Nat. Univ. Ireland, Galway, Ireland)

## EXISTENCE OF GLOBAL SOLUTIONS FOR SOME CLASSES OF INTEGRAL EQUATIONS

## ІСНУВАННЯ ГЛОБАЛЬНИХ РОЗВ'ЯЗКІВ ДЕЯКИХ КЛАСІВ ІНТЕГРАЛЬНИХ РІВНЯНЬ

We study the existence of  $L^p$ -solutions for a class of Hammerstein integral equations and neutral functional differential equations involving abstract Volterra operators. Using compactness-type conditions, we establish the global existence of solutions. In addition, a global existence result for a class of nonlinear Fredholm functional integral equations involving abstract Volterra equations is given.

Вивчається існування  $L^p$ -розв'язків для класу інтегральних рівнянь Гаммерштейна та нейтральних функціональних диференціальних рівнянь з абстрактними операторами Вольтерра. Існування глобальних розв'язків встановлено за допомогою умов типу компактності. Крім того, наведено результат про глобальне існування розв'язку для класу нелінійних функціональних інтегральних рівнянь Фредгольма з абстрактними операторами Вольтерра.

1. Introduction. Many problems arising in modeling real world phenomena lead to mathematical models described by nonlinear integral equations in abstract spaces. The theory of nonlinear integral equations in abstract spaces, is a relatively old theory, but it is also current and has important applications in physics, engineering and biology. The concept of abstract Volterra operator (or causal operator), introduced by [47] and [46], plays an important role in physics and engineering [25, 42]. This concept arises naturally in classes of differential equations and integral equations such as ordinary differential equations, integro-differential equations, differential equations with finite or infinite delay, Volterra integral equations, neutral functional equations, and so on.

Let E be a real Banach space,  $L^p([0,a],E)$  be the space of all (classes of) strongly measurable and Bochner integrable functions  $u:[0,a]\to E$ , and  $\mathcal{L}(E)$  the space of all bounded linear operators from E into itself. In this paper, we consider the Hammerstein integral equation

$$u(t) = (\mathfrak{P}u)(t) + \lambda \int_{0}^{a} K(t,s)(\mathfrak{Q}u)(s)ds, \quad \text{a.e.} \quad t \in [0,a],$$
 (1.1)

and the Volterra-Hammerstein integral equation

$$u(t) = (\mathfrak{P}u)(t) + \int_{0}^{t} K(t,s)(\mathfrak{Q}u)(s)ds,$$
 a.e.  $t \in [0,a],$  (1.2)

where  $\mathfrak{P},\mathfrak{Q}:L^p([0,a],E)\to L^p([0,a],E)$  are continuous abstract Volterra operators,  $K:[0,a]\times [0,a]\to \mathcal{L}(E)$  is strongly measurable,  $\lambda\in\mathbb{R}$ , and we provide conditions under which these equations have solutions in  $L^p([0,a],E)$ . In addition, under suitable conditions we establish the existence of continuous solutions for the following nonlinear Fredholm functional-integral equation:

$$x(t) = x_0(t) + \int_0^a F(t, s, (\mathfrak{Q}x)(s)) ds, \quad t \in [0, a],$$

where  $F(\cdot,\cdot,\cdot):[0,a]\times[0,a]\times Y\to X$  is a Carathéodory function,  $\mathfrak{Q}:C([0,a],X)\to L^\infty([0,a],Y)$  is a continuous causal operator,  $x_0(\cdot)\in C([0,a],X)$ , and X,Y are infinite dimensional spaces.

We recall that an operator  $Q: L^p([0,a], E) \to L^p([0,a], E)$  is called an abstract Volterra operators (or a causal operator) if, for each  $\tau \in [0,a)$  and for all  $u,v \in L^p([0,a], E)$  with u(t) = v(t) for every  $t \in [0,\tau]$ , we have Qu(t) = Qv(t) for a.e.  $t \in [0,\tau]$ .

The study of differential equations involving abstract Volterra operators can be found in the monographs [10, 19, 32, 40], and also in the papers [1, 2, 4, 11, 12, 14, 24, 34, 35, 37, 38, 41, 48, 50, 51]. The existence of  $L^p$ -solutions for different classes of differential equations and integral equations were studied in [3, 6–9, 16, 26, 30, 31, 33, 36, 39, 43].

**2. Preliminaries.** Let E be a real Banach space endowed with the norm  $\|\cdot\|$ . If A is a nonempty subset in E, then  $\overline{A}$ ,  $\operatorname{conv}(A)$  and  $\overline{\operatorname{conv}}(A)$  denote the closure of A, the convex hull of A and the closure of the convex hull of A, respectively. We denote by C([0,a],E) the Banach space of continuous bounded functions from [0,a] into E endowed with the norm  $\|u(\cdot)\| = \sup_{0 \le t \le a} \|u(t)\|$ . The space of all (classes of) strongly measurable functions  $u:[0,a] \to E$  such that

$$||u||_p := \left(\int_0^a ||u(t)||^p\right)^{1/p} < \infty$$

for  $1 \leq p < \infty$ , will be denoted by  $L^p([0,a],E)$ . Then  $L^p([0,a],E)$  is a Banach space with respect to the norm  $\|u\|_p$ . Also, we denote by  $L^\infty([0,a],E)$  the space of all (classes of) strongly measurable functions  $u(\cdot):[0,a]\to E$  which are essentially bounded on [0,a]. Then  $L^\infty([0,a],E)$  is a Banach space with respect to the norm

$$\|u\|_{\infty} := \underset{t \in [0,a]}{\operatorname{ess \, sup}} \|u(t)\| = \inf\{M \geq 0; \|u(t)\| \leq M \qquad \text{ for a.e.} \quad t \in [0,a]\}.$$

We recall that, if  $1 \le p < q \le \infty$ , then

$$L^{q}([0,a],E) \subset L^{p}([0,a],E)$$

and

$$||u||_p \le a^{1/p-1/q} ||u||_q$$
 for every  $u(\cdot) \in L^q([0, a], E)$ .

In the following, for a given  $p \ge 1$ , we shall denote by  $p' \ge 1$  its conjugate; that is,  $\frac{1}{p} + \frac{1}{p'} = 1$ . We denote the space of all bounded linear operators acting on a Banach space E by  $\mathcal{L}(E)$ . Then  $\mathcal{L}(E)$  is a Banach space with respect to the norm

$$||T|| := \inf\{M \ge 0; ||Tu|| \le M||u|| \text{ for all } u \in E\}, \quad T \in \mathcal{L}(E).$$

We denote by  $\beta(A)$  the Hausdorff measure of non-compactness of a nonempty bounded set  $A \subset E$ , and it is defined by [27]:

$$\beta(A) = \inf\{\varepsilon > 0; A \text{ admits a finite cover by balls of radius } \le \varepsilon\}.$$

The Kuratowski measure of non-compactness of a nonempty bounded set  $A \subset E$  is defined by [29]:

 $\alpha(A) = \inf \Big\{ \delta > 0; \quad A \quad \text{can be expressed as the union of a finite number of sets} \\$ 

such that the diameter of each set does not exceed  $\delta$ ,

where the diameter of a bounded set  $A \subset E$  is defined by  $\dim(A) = \sup\{\|x - y\|; x, y \in A\}$ .

Let  $\gamma(\cdot)$  be either  $\alpha(\cdot)$  or  $\beta(\cdot)$ . If A, B are bounded subsets of E, then (see [5, 27]):

- (1)  $\gamma(A) = 0$  if and only if  $\overline{A}$  is compact;
- (2)  $\gamma(A) = \gamma(\overline{A}) = \gamma(\overline{\text{conv}}(A));$
- (3)  $\gamma(\lambda A) = |\lambda| \gamma(A)$  for every  $\lambda \in \mathbb{R}$ ;
- (4)  $\gamma(A) \leq \gamma(B)$  if  $A \subset B$ ;
- (5)  $\gamma(A+B) \leq \gamma(A) + \gamma(B)$ ;
- (6) if  $T: E \to E$  is a bounded linear operator, then  $\gamma(TA) \le ||T|| \gamma(A)$ ;
- (7) if  $\{A_n\}_{n\geq 1}$  is a decreasing sequence of bounded closed nonempty subsets of E and  $\lim_{n\to\infty}\gamma(A_n)=0$ , then  $\bigcap_{n=1}^{\infty}A_n$  is a nonempty and compact subset of E [29].

**Remark 2.1.** In general, for any bounded set  $A \subset E$ , one has  $\beta(A) \leq \alpha(A) \leq 2\beta(A)$  and both inequalities can be strict. Also, for any bounded set  $A \subset E$ , we have that  $\gamma(A) \leq \dim(A)$  and  $\gamma(A) \leq 2d$  if  $\sup_{x \in A} \|x\| \leq d$ .

We recall the following lemma due to Heinz [21].

**Lemma 2.1.** Let  $\{u_n(\cdot); n \geq 1\}$  be a sequence in  $L^1([0,a],E)$  such that there exists  $m(\cdot) \in L^1([0,a],\mathbb{R}_+)$  with  $||u_n(t)|| \leq m(t)$  for each  $n \geq 1$  and for a.e.  $t \in [0,a]$ . Then the function  $t \mapsto \psi(t) := \gamma(\{u_n(t); n \geq 1\})$  is integrable on [0,a] and, for each  $t \in [0,a]$ , we have

(a) (Heinz [21])

$$\alpha\left(\left\{\int_{0}^{t} u_n(s)ds; n \ge 1\right\}\right) \le 2\int_{0}^{t} \psi(s)ds,$$

(b) (Kisielewicz [28], Lemma 2.2)

$$\beta\left(\left\{\int_{0}^{t} u_{n}(s)ds; n \ge 1\right\}\right) \le \int_{0}^{t} \psi(s)ds,$$

provided that E is a separable banach space.

In the following, we let  $\alpha_p(\cdot)$  denote the Kuratowski measures of noncompactness of sets in the space  $L^p([0,a],E)$ .

**Lemma 2.2.** Let  $1 \le p < \infty$  and let  $V \subset L^p([0, a], E)$  be a countable set such that there exists  $m(\cdot) \in L^1([0, b], \mathbb{R}_+)$  with  $||u(t)|| \le m(t)$  for each  $u(\cdot) \in A$  and for a.e.  $t \in [0, a]$ .

(a) [43, 44] *If* 

$$\lim_{h \to 0} \sup_{u \in A} \int_{0}^{a} \|u(t+h) - u(t)\|^{p} dt = 0, \tag{2.1}$$

then

$$\alpha_p(A) \le 2 \left( \int_0^a \left[ \alpha(V(t)) \right]^p dt \right)^{1/p}.$$

- (b) [20] (Theorem 1.2.8) The set V is relatively compact in  $L^p([0,a],E)$  if and only if (2.1) is satisfied and V(t) is relatively compact in E for a.e.  $t \in [0, a]$ .
- 3. A global existence results for Hammerstein integral equations. Let p and q be real numbers such that  $q > p \ge 1$  and  $p\left(1 - \frac{1}{q}\right) > 1$ . We also assume that  $(H_1) \mathfrak{P}, \mathfrak{Q}: L^p([0,a],E) \to L^p([0,a],E)$  are continuous operators such that there exist  $b(\cdot), c(\cdot) \in \mathbb{R}$
- $\in L^p([0,a],\mathbb{R}_+)$  and d>0 with

$$\|(\mathfrak{P}u)(t)\| \leq b(t) \quad \text{ and } \quad \|(\mathfrak{Q}u)(t)\| \leq c(t) + d\|u(t)\| \quad \text{ for a.e.} \quad t \in [0,a]$$
 and for every  $u(\cdot) \in L^p([0,a],E)$ ;

(H<sub>2</sub>) K is a strongly measurable function from  $[0, a] \times [0, a]$  into  $\mathcal{L}(E)$  and

$$\operatorname{ess\,sup}_{s\in[0,a]}\left(\int\limits_0^a\|K(t,s)\|^qdt\right)^{1/q}:=M<\infty.$$

**Lemma 3.1.** If  $(H_2)$  holds, then

$$\lim_{h \to 0} \int_{0}^{a} \left( \int_{0}^{a} \|K(t+h,s) - K(t,s)\|^{q} dt \right)^{1/q} ds = 0.$$
 (3.1)

**Proof.** For a.e.  $s \in [0, a]$ , let us define the function  $\psi_s(\cdot): [0, a] \to \mathcal{L}(E)$  by  $\psi_s(t) = K(t, s)$ ,  $t \in [0,a]$ . From (H<sub>2</sub>) it follows that  $\|\psi_s(\cdot)\|_q \in L^\infty([0,a],\mathbb{R}_+)$  and  $\|\psi_s(\cdot)\|_q \leq M < \infty$  for a.e.  $s \in [0,a]$ , so that  $\psi_s(\cdot) \in L^q([0,a],\mathcal{L}(E))$  for a.e.  $s \in [0,a]$ . Let  $\{h_n\}_{n \geq 1}$  be a sequence of real positive numbers such that  $h_n \to 0$  as  $n \to \infty$ , and  $t + h_n \in [0, a)$  for every  $t \in [0, a)$  and  $n \ge 1$ . Also, for a.e.  $s \in [0, a]$ , let

$$\theta_n(s) := \left( \int_0^a \|\psi_s(t+h_n) - \psi_s(t)\|^q dt \right)^{1/q} =$$

$$= \left( \int_0^a \|K(t+h_n,s) - K(t,s)\|^q dt \right)^{1/q}, \quad n \ge 1.$$

Since  $\psi_s(\cdot) \in L^q([0,a],\mathcal{L}(E))$  for a.e.  $s \in [0,a]$ , then from the fact that translations of  $L^p$  functions  $(1 \le p < \infty)$  are continuous in norm, we see that

$$\lim_{n\to\infty} \left(\int\limits_0^a \|\psi_s(t+h_n)-\psi_s(t)\|^q dt\right)^{1/q} = 0 \qquad \text{for a.e.} \quad s\in[0,a],$$

so that  $\lim_{n\to\infty} \theta_n(s) = 0$  for a.e.  $s \in [0, a]$ . On the other hand, since  $(H_2)$  implies

$$0 \le \theta_n(s) \le \|\theta_n\|_{\infty} \le 2M$$
 for a.e.  $s \in [0, a]$  and all  $n \ge 1$ ,

then, by the Dominated Convergence Theorem, we have  $\lim_{n\to\infty}\int_0^u \theta_n(s)\,ds=0$ , so (3.1) is proved.

**Lemma 3.2.** If  $(H_2)$  holds, then the function  $\xi(\cdot): [0,a] \to \mathbb{R}_+$ , defined by

$$\xi(t) = \left(\int_{0}^{a} \|K(t,s)\|^{q'} ds\right)^{1/q'} \quad \text{for a.e.} \quad t \in [0,a],$$
 (3.2)

belongs to  $L^q([0,a],\mathbb{R}_+)$ . Moreover,  $\|\xi\|_q \leq Ma^{1/q'}$  and  $\|\xi\|_p \leq Ma^{1/p-1/q+1/q'}$ . **Proof.** From (H<sub>2</sub>) and Tonelli's theorem it is easy to see that the function  $\xi(\cdot):[0,a]\to\mathbb{R}_+$ is measurable on [0,a]. Now, from q>p and  $p\left(1-\frac{1}{q}\right)>1$  it follows that q'< p< q; that is q/q' > 1. Then, from (H<sub>2</sub>) and the integral version of Minkowski's inequality, we have

$$\int_{0}^{a} \xi^{q}(t)dt = \int_{0}^{a} \left( \int_{0}^{a} \|K(t,s)\|^{q'} ds \right)^{q/q'} dt \le$$

$$\le \left[ \int_{0}^{a} \left( \int_{0}^{a} \|K(t,s)\|^{q} dt \right)^{q'/q} ds \right]^{q/q'} \le M^{q} a^{q/q'},$$

so that  $\xi(\cdot) \in L^q([0,a],\mathbb{R}_+)$  and  $\|\xi\|_q \leq Ma^{1/q'}$ . Since p < q,  $\|\xi\|_p \leq a^{1/p-1/q}\|\xi\|_q \leq a^{1/p-1/q}\|\xi\|_q$  $< Ma^{1/p-1/q+1/q'}$ .

**Theorem 3.1.** Let conditions  $(H_1)$ ,  $(H_2)$  be satisfied. Suppose that there exist  $k_1 \in [0,1)$  and  $k_2 > 0$  such that

$$\alpha((\mathfrak{P}A)(t)) \le k_1 \alpha(A(t))$$
 and  $\alpha((\mathfrak{Q}A)(t)) \le k_2 \alpha(A(t))$  (3.3)

for  $t \in [0, a]$  and for each bounded subset  $A \subset L^p([0, a], E)$ .

Then there exists a positive number  $\lambda_0$  such that for every  $\lambda \in R$  with  $|\lambda| < \lambda_0$ , the integral equation (1.1) has at least one solution in  $L^p([0,a],E)$ .

**Proof.** First, we show that each solution of (1.1) is a priori bounded in  $L^p([0,a],E)$ . Indeed, since

$$||u(t)|| \le b(t) + |\lambda| \int_{0}^{a} ||K(t,s)|| ||(\mathfrak{Q}u)(s)|| ds, \quad t \in [0,a],$$

then, using the Minkowski's inequality and the integral version of Minkowski inequality, we obtain

$$||u||_{p} \leq \left(\int_{0}^{a} |b(t)|^{p} dt\right)^{1/p} + |\lambda| \left[\int_{0}^{a} \left(\int_{0}^{a} ||K(t,s)||| (\mathfrak{Q}u)(s)|| ds\right)^{p} dt\right]^{1/p} \leq$$

$$\leq ||b||_{p} + |\lambda| \int_{0}^{a} \left[\int_{0}^{a} [||K(t,s)||| (\mathfrak{Q}u)(s)||]^{p} dt\right]^{1/p} ds \leq$$

$$\leq ||b||_{p} + |\lambda| \int_{0}^{a} ||(\mathfrak{Q}u)(s)|| \left(\int_{0}^{a} ||K(t,s)||^{p} dt\right)^{1/p} ds.$$

Since q > p then, using (H<sub>1</sub>), (H<sub>2</sub>) and Hölder's inequality, we get

$$\begin{split} \int\limits_0^a \|(\mathfrak{Q}u)(s)\| \left(\int\limits_0^a \|K(t,s)\|^p dt\right)^{1/p} ds &\leq \\ &\leq a^{1/p-1/q} \int\limits_0^a \|(\mathfrak{Q}u)(s)\| \left(\int\limits_0^a \|K(t,s)\|^q dt\right)^{1/q} ds &\leq \\ &\leq Ma^{1/p-1/q} \int\limits_0^a \|(\mathfrak{Q}u)(s)\| ds &\leq Ma^{1/p-1/q}a^{1/p'} \left(\int\limits_0^a \|(\mathfrak{Q}u)(s)\|^p ds\right)^{1/p} &\leq \\ &\leq Ma^{1/q'} \left(\|c\|_p + d\|u\|_p\right), \end{split}$$

so that

$$||u(\cdot)||_p \le ||b(\cdot)||_p + |\lambda| M a^{1/q'} (||c(\cdot)||_p + d||u(\cdot)||_p).$$

Put

$$\lambda_0 := \min \left\{ \frac{1}{dMa^{1/q'}}, \frac{1 - k_1}{2k_2a^{1/p - 1/q}\|\xi\|_p} \right\},$$

where the function  $\xi(\cdot)$  is defined in (3.2). Then for each  $|\lambda| < \lambda_0$ , we have  $||u||_p \le r$ , where  $r := \gamma (1-\rho)^{-1}, \; \rho := |\lambda| dM a^{1/q'} < 1$  and  $\gamma := ||b||_p + |\lambda| M a^{1/q'} ||c||_p$ , so that u bounded in  $L^p([0,a],E)$ . Moreover, we remark that  $\|\mathfrak{Q}u\|_p \le \|c\|_p + dr$  if  $\|u\|_p \le r$ . We also notice that

$$||u(t)|| \le b(t) + |\lambda| a^{1/p - 1/q} (||c||_p + dr) \xi(t)$$
 for a.e.  $t \in [0, a]$ ;

that is, for every  $u \in B$ , we have

$$||u(t)|| \le \varphi(t) \qquad \text{for a.e.} \quad t \in [0, a], \tag{3.4}$$

where  $\varphi(t) = b(t) + |\lambda| a^{1/p-1/q} (\|c\|_p + dr) \xi(t), \ t \in [0, a] \text{ and } B := \{u(\cdot) \in L^p([0, a], E); \|u\|_p \le \le r\}.$  Moreover, from Lemma 3.2 it follows that  $\varphi(\cdot) \in L^p([0, a], \mathbb{R}_+)$ , and

$$\|\varphi\|_{p} \le \|b\|_{p} + |\lambda| M a^{2(1/p - 1/q) + 1/q'} (\|c\|_{p} + dr). \tag{3.5}$$

Now, define the operator  $\mathfrak{T}: L^p([0,a],E) \to L^p([0,a],E)$  by

$$(\mathfrak{T}u)(t) = (\mathfrak{P}u)(t) + \lambda \int_{0}^{a} K(t,s)(\mathfrak{Q}u)(s)ds, \quad t \in [0,a].$$
(3.6)

As above, we can show that

$$\|(\mathfrak{T}u)(t)\| \le \varphi(t)$$
 for a.e.  $t \in [0, a]$ ,

and

$$\|\mathfrak{T}u\|_p \le \|b\|_p + |\lambda| Ma^{1/q'} (\|c\|_p + d\|u\|_p),$$

for every  $u(\cdot) \in L^p([0,a],E)$ , so that  $\mathfrak T$  is well defined. Moreover, it is easy to see that  $\mathfrak T(B) \subset B$ ; that is,  $\mathfrak T$  is an operator from B into itself. Next, we show that  $\mathfrak T$  is a continuous operator. For this, let  $\{u_n(\cdot)\}_{n\geq 1}$  be a convergent sequence in  $L^p([0,a],E)$  such that  $u_n(\cdot) \to u(\cdot)$  as  $n\to\infty$ . Since

$$\| (\mathfrak{T}u_n) (t) - (\mathfrak{T}u) (t) \| \le \| (\mathfrak{P}u_n) (t) - (\mathfrak{P}u) (t) \| +$$

$$+ |\lambda| \int_{0}^{a} \| K(t,s) \| \| (\mathfrak{Q}u_n)(s) - (\mathfrak{Q}u)(s) \| ds$$

for every  $t \in [0, a]$ , then using Minkowski's inequality we have

$$\|\mathfrak{T}u_{n} - \mathfrak{T}u\|_{p} \leq \left(\int_{0}^{a} \|(\mathfrak{P}u_{n})(t) - (\mathfrak{P}u)(t)\|^{p} dt\right)^{1/p} +$$

$$+|\lambda| \left[\int_{0}^{a} \left(\int_{0}^{a} \|K(t,s)\|\|(\mathfrak{Q}u_{n})(s) - (\mathfrak{Q}u)(s)\| ds\right)^{p} dt\right]^{1/p}.$$
(3.7)

Now, using (H<sub>2</sub>) and the integral version of Minkowski inequality, we obtain

$$\left[ \int_{0}^{a} \left( \int_{0}^{a} \|K(t,s)\| \|(\mathfrak{Q}u_{n})(s) - (\mathfrak{Q}u)(s)\| ds \right)^{p} dt \right]^{1/p} \leq$$

$$\leq \int_{0}^{a} \left[ \int_{0}^{a} \left[ \|K(t,s)\| \|(\mathfrak{Q}u_{n})(s) - (\mathfrak{Q}u)(s)\| \right]^{p} dt \right]^{1/p} ds \leq$$

$$\leq \int_{0}^{a} \|(\mathfrak{Q}u_{n})(s) - (\mathfrak{Q}u)(s)\| \left( \int_{0}^{a} \|K(t,s)\|^{p} dt \right)^{1/p} ds \leq$$

$$\leq a^{1/p-1/q} \int_{0}^{a} \|(\mathfrak{Q}u_{n})(s) - (\mathfrak{Q}u)(s)\| \left( \int_{0}^{a} \|K(t,s)\|^{q} dt \right)^{1/q} ds \leq$$

$$\leq Ma^{1/p-1/q} a^{1/p'} \left( \int_{0}^{a} \|(\mathfrak{Q}u_{n})(s) - (\mathfrak{Q}u)(s)\|^{p} ds \right)^{1/p} =$$

$$= Ma^{1/q'} \|\mathfrak{Q}u_{n} - \mathfrak{Q}u\|_{p},$$

so that (3.7) become

$$\|\mathfrak{T}u_n - \mathfrak{T}u\|_p \le \|\mathfrak{P}u_n - \mathfrak{P}u\|_p + M|\lambda|a^{1/q'}\|\mathfrak{Q}u_n - \mathfrak{Q}u\|_p.$$

Since  $\mathfrak P$  and  $\mathfrak Q$  are continuous operators, from the above inequality it follows that  $\|\mathfrak T u_n - \mathfrak T u\|_p \to 0$  as  $n \to \infty$ , and so  $\mathfrak T$  is a continuous operator. In the next step, we will show that

$$\lim_{h \to 0} \sup_{u \in B} \int_{0}^{a} \|(\mathfrak{T}u)(t+h) - (\mathfrak{T}u)(t)\|^{p} dt = 0.$$
 (3.8)

If  $t \in [0,a]$  and  $t+h \in [0,a]$ , then for every  $u(\cdot) \in B$  we have

$$\|(\mathfrak{T}u)(t+h) - (\mathfrak{T}u)(t)\| \le \|(Pu)(t+h) - (Pu)(t)\| + \|\lambda\| \int_{0}^{a} \|K(t+h,s) - K(t,s)\| \|(\mathfrak{Q}u)(s)\| ds.$$

Using Minkowski's inequality, we obtain

$$J := \left( \int_{0}^{a} \|(\mathfrak{T}u)(t+h) - (\mathfrak{T}u)(t)\|^{p} dt \right)^{1/p} \le \left( \int_{0}^{a} \|(\mathfrak{P}u)(t+h) - (\mathfrak{P}u)(t)\|^{p} dt \right)^{1/p} +$$

$$+ |\lambda| \left[ \int_{0}^{a} \left( \int_{0}^{a} \|K(t+h,s) - K(t,s)\| \|(\mathfrak{Q}u)(s)\| ds \right)^{p} dt \right]^{1/p} = J_{1} + J_{2}.$$

$$(3.9)$$

Since  $\mathfrak{P}u \in L^p([0,a],E)$ , then from the fact that translations of  $L^p$ -functions  $(1 \le p < \infty)$  are continuous in norm, we see that  $J_1 \to 0$  as  $h \to 0$ .

Next, using the integral version of Minkowski inequality, we get

$$\begin{split} J_2 & \leq \int\limits_0^a \left( \int\limits_0^a \left[ \|K(t+h,s) - K(t,s)\| \|(\mathfrak{Q}u)(s)\| \right]^p dt \right)^{1/p} ds = \\ & = \int\limits_0^a \|(\mathfrak{Q}u)(s)\| \left( \int\limits_0^a \|K(t+h,s) - K(t,s)\|^p dt \right)^{1/p} ds \leq \\ & \leq a^{1/p-1/q} \int\limits_0^a \|(\mathfrak{Q}u)(s)\| \left( \int\limits_0^a \|K(t+h,s) - K(t,s)\|^q dt \right)^{1/q} ds \leq \\ & \leq a^{1/p-1/q} \left( \int\limits_0^a \|(\mathfrak{Q}u)(s)\|^{q'} ds \right)^{1/q'} \left[ \int\limits_0^a \left( \int\limits_0^a \|K(t+h,s) - K(t,s)\|^q dt \right) ds \right]^{1/q} \leq \\ & \leq a^{1/q'-1/q} \|\mathfrak{Q}u\|_p \left[ \int\limits_0^a \left( \int\limits_0^a \|K(t+h,s) - K(t,s)\|^q dt \right) ds \right]^{1/q}, \end{split}$$

so that

$$J_2^q \le a^{q/q'-1} (\|c\|_p + dr)^q \int_0^a \left( \int_0^a \|K(t+h,s) - K(t,s)\|^q dt \right) ds.$$

Then, from Lemma 3.1, we have  $J_2 \to 0$  as  $h \to 0$ . Therefore, from (3.9) it follows that

$$J^p = \int_0^a \|(\mathfrak{T}u)(t+h) - (\mathfrak{T}u)(t)\|^p dt \to 0$$
 as  $h \to 0$ ,

uniformly with respect to  $u \in B$ , so that (3.8) is proved. Next, let A be a countable subset of B such that  $A \subset \overline{\operatorname{co}}((\mathfrak{T}A) \cup \{0\})$ . We will use the compactness criteria from Lemma 2.2 to show that A is a relatively compact set in  $L^p([0,a],E)$ . First, from (3.8) we have

$$\lim_{h \to 0} \sup_{u \in A} \int_{0}^{a} \|u(t+h) - u(t)\|^{p} dt = 0.$$
(3.10)

Since A is a bounded set in  $L^p([0,a],E)$  then, from (3.10) and Lemma 2.2, we have

$$\alpha_p(A) \le 2 \left( \int_0^a \left[ \alpha(A(t)) \right]^p dt \right)^{1/p}. \tag{3.11}$$

On the other hand, using the properties of the Kuratowski measures of noncompactness and (3.3), we have

$$\alpha(A(t)) \leq \alpha \left(\overline{\operatorname{co}}((\mathfrak{T}A)(t) \cup \{0\})\right) = \alpha \left((\mathfrak{T}A)(t)\right) \leq$$

$$\leq \alpha \left((\mathfrak{P}A)(t) + \lambda \int_{0}^{a} K(t,s)(\mathfrak{Q}A)(s)ds\right) \leq$$

$$\leq \alpha \left((\mathfrak{P}A)(t)\right) + |\lambda|\alpha \left(\int_{0}^{a} K(t,s)(\mathfrak{Q}A)(s)ds\right) \leq$$

$$\leq k_{1}\alpha(A(t)) + |\lambda|\alpha \left(\int_{0}^{a} K(t,s)(\mathfrak{Q}A)(s)ds\right). \tag{3.12}$$

Next, for each  $u(\cdot) \in A$ , the function  $s \mapsto \|K(t,s)(\mathfrak{Q}u)(s)\|$  is measurable on [0,t] for a.e.  $t \in [0,a]$ . From (3.4) it follows that

$$||K(t,s)(\mathfrak{Q}u)(s)|| \le ||K(t,s)||(c(s)+d||u(t)||) \le ||K(t,s)||(c(s)+d\varphi(t)),$$

and consequently

$$\int_{0}^{a} \|K(t,s)(\mathfrak{Q}u)(s)\|ds \le \left(\int_{0}^{a} \|K(t,s)\|^{q'}ds\right)^{1/q'} \left(\int_{0}^{a} (c(s) + d\varphi(t))^{q} ds\right)^{1/q} \le$$

$$\le a^{1/p - 1/q} (\|c\|_{p} + d\|\varphi\|_{p}) \xi(t),$$

so that  $s \mapsto \|K(t,s)(Qu)(s)\|$  belong to  $L^1([0,a],\mathbb{R}_+)$  for a.e.  $t \in [0,a]$ . Hence, from Lemma 3.1, Hölder's inequality and Lemma 3.2, we have

$$\alpha \left( \int_{0}^{a} K(t,s)(\mathfrak{Q}A)(s) ds \right) \leq 2 \int_{0}^{a} \alpha \left( K(t,s)(\mathfrak{Q}A)(s) \right) ds \leq$$

$$\leq 2k_{2} \int_{0}^{a} \|K(t,s)\| \alpha \left( (A)(s) \right) ds \leq$$

$$\leq 2k_{2} \left( \int_{0}^{a} \|K(t,s)\|^{q'} ds \right)^{1/q'} \left( \int_{0}^{a} \left[ \alpha \left( (A)(s) \right) \right]^{q} ds \right)^{1/q} \leq$$

$$\leq 2k_{2}a^{1/p-1/q} \left( \int_{0}^{a} \left[ \alpha \left( (A)(s) \right) \right]^{p} ds \right)^{1/p} \xi(t), \tag{3.13}$$

so that, from (3.12) and Lemma 2.2, we obtain

$$\left(\int_{0}^{a} \left[\alpha\left((A)(s)\right)\right]^{p} ds\right)^{1/p} \leq k_{1} \left(\int_{0}^{a} \left[\alpha\left((A)(s)\right)\right]^{p} ds\right)^{1/p} + \\
+2k_{2}|\lambda|a^{1/p-1/q}||\xi||_{p} \left(\int_{0}^{a} \left[\alpha\left((A)(s)\right)\right]^{p} ds\right)^{1/p} \leq \\
\leq (k_{1} + 2|\lambda|k_{2}a^{1/p-1/q}||\xi||_{p}) \left(\int_{0}^{a} \left[\alpha\left((A)(s)\right)\right]^{p} ds\right)^{1/p}.$$
(3.14)

Since  $k_1 + 2|\lambda|k_2a^{1/p-1/q}||\xi||_p < 1$ , from the last inequality we obtain

$$\left(\int_{0}^{a} \left[\alpha\left((A)(s)\right)\right]^{p} ds\right)^{1/p} = 0$$

and thus, from (3.11) it follows that  $\alpha_p(A)=0$ ; that is, A is a relatively compact set in  $L^p([0,a],E)$ . Summarizing, we have shown that  $\mathfrak{T}\colon B\to B$  is a continuous operator with the property that for a countable subset A of B such that  $A\subset \overline{\operatorname{co}}((\mathfrak{T}A)\cup\{0\})$  we have that A is relatively compact. Since B is a closed and convex set in  $L^p([0,a],E)$  then, by the Mönch fixed point theorem, it follows that there exists  $u(\cdot)\in B$  such that  $u=\mathfrak{T}u$ ; that is, the integral equation (1.1) has a least one solution  $u(\cdot)\in B$ .

Theorem 3.1 is proved.

**Remark 3.1.** Suppose that  $\lambda=1$  and the conditions (H<sub>1</sub>), (H<sub>2</sub>) are satisfied. If (3.3) holds for some  $k_1,k_2\geq 0$  with  $k_1+2k_2a^{1/p-1/q}\|\xi\|_p<1$ , then from the above proof it is easy to see that the integral equation (1.1) has at least one solution in  $L^p([0,a],E)$ .

**Theorem 3.2.** Let conditions (H<sub>1</sub>), (H<sub>2</sub>) be satisfied and suppose that (3.3) holds for some  $k_1, k_2 \ge 0$  with  $k_1 + 2k_2a^{1/p-1/q}\|\xi\|_p < 1$ . Then the integral equation (1.2) has at least one solution in  $L^p([0,a],E)$ .

**Proof.** If we put

$$K^*(t,s) := \begin{cases} K(t,s) & \text{if } 0 \le s \le t \le a, \\ 0 & \text{otherwise,} \end{cases}$$

and  $\lambda = 1$ , then the integral equation (1.2) is equivalent to

$$u(t) = (\mathfrak{P}u)(t) + \int_{0}^{a} K^{*}(t,s)(\mathfrak{Q}u)(s)ds$$
 a.e.  $t \in [0,a]$ . (3.15)

Since K satisfies (H<sub>2</sub>), it follows that  $K^*$  is a strongly measurable function from  $[0, a] \times [0, a]$  into  $\mathcal{L}(E)$ ,

$$\operatorname{ess\,sup}_{s \in [0,a]} \left( \int_{0}^{a} \|K^{*}(t,s)\|^{q} dt \right)^{1/q} := M < \infty,$$

and

$$\lim_{h \to 0} \int_{0}^{a} \left( \int_{0}^{a} \|K^{*}(t+h,s) - K^{*}(t,s)\|^{q} dt \right)^{1/q} ds = 0.$$

Also, it is easy to check that the function  $\xi^* : [0, a] \to \mathbb{R}_+$ , defined by

$$\xi^*(t) = \left(\int\limits_0^a \|K^*(t,s)\|^{q'} ds\right)^{1/q'}$$
 for a.e.  $t \in [0,a]$ ,

belongs to  $L^q([0,a],\mathbb{R}_+)$ ,  $\|\xi^*\|_q \leq Ma^{1/q'}$  and  $\|\xi^*\|_p \leq Ma^{1/p-1/q+1/q'}$ . Then, by Remark 3.1, it follows that the integral equation (3.15) has at least one solution in  $L^p([0,a],E)$ , so that the integral equation (1.2) has at least one solution in  $L^p([0,a],E)$ .

Theorem 3.2 is proved.

**Remark 3.2.** Suppose that there exist  $m_0 > 0$ ,  $k_2 > 0$  such that

$$\alpha((\mathfrak{P}A)(t)) \le m_0 \left( \int_0^t \left[ \alpha(A(s)) \right]^p ds \right)^{1/p} \quad \text{and} \quad \alpha((\mathfrak{Q}A)(t)) \le k_2 \alpha(A(t)) \tag{3.16}$$

for  $t \in [0, a]$  and for each bounded subset  $A \subset L^p([0, a], E)$ . We notice that if there exists  $m_1 > 0$  such that

$$\alpha((\mathfrak{P}A)(t)) \le m_1 \int_0^t \alpha(A(s))ds, \quad t \in [0, a],$$

then

$$\alpha((\mathfrak{P}A)(t)) \le m_1 a^{1/p'} \left( \int_0^t \left[ \alpha(A(s)) \right]^p ds \right)^{1/p},$$

so that  $\mathfrak{P}$  satisfies (3.16) with  $m_0 := m_1 a^{1/p'}$ . Now, let A be a countable subset of B such that  $A \subset \overline{\operatorname{co}}((\mathfrak{T}A) \cup \{0\})$ , where  $\mathfrak{T}$  is defined by (3.6) and  $B := \{u \in L^p([0,a],E); \|u\|_p \leq r\}$ . Then (3.12) becomes

$$\alpha(A(t)) \le m_0 \left( \int_0^t \left[ \alpha(A(s)) \right]^p ds \right)^{1/p} + |\lambda| \alpha \left( \int_0^a K(t, s) (\mathfrak{Q}A)(s) ds \right)$$
(3.17)

for all  $t \in [0, a]$ . Then, by (3.13), (3.14) and (3.17), we obtain

$$\left(\int_{0}^{a} \left[\alpha\left((A)(s)\right)\right]^{p} ds\right)^{1/p} \leq m_{0} \left(\int_{0}^{a} \left[\alpha\left((A)(s)\right)\right]^{p} ds\right)^{1/p} + 2k_{2}|\lambda|a^{1/p-1/q}||\xi||_{p} \left(\int_{0}^{a} \left[\alpha\left((A)(s)\right)\right]^{p} ds\right)^{1/p} \leq \left(m_{0} + 2|\lambda|k_{2}a^{1/p-1/q}||\xi||_{p}\right) \left(\int_{0}^{a} \left[\alpha\left((A)(s)\right)\right]^{p} ds\right)^{1/p}.$$

If  $m_0 + 2|\lambda|k_2a^{1/p-1/q}||\xi||_p < 1$ , then the last inequality implies

$$\left(\int_{0}^{a} \left[\alpha\left((A)(s)\right)\right]^{p} ds\right)^{1/p} = 0.$$

Therefore, under conditions (H<sub>1</sub>), (H<sub>2</sub>) the result of Theorem 3.1 remains true if (3.16) holds for some  $m_0 > 0$ . Consequently, the result of Theorem 3.2 remains also true if (3.16) holds for some  $m_0 > 0$  with  $m_0 + 2k_2a^{1/p-1/q}\|\xi\|_p < 1$ .

**4. Neutral functional differential equation.** The aim of this section is to apply Theorem 3.2 to a class of neutral functional differential equations involving abstract Volterra equations. Some interesting results about neutral differential equations can be found in [17, 18, 22, 23]. In the following, we consider the neutral functional differential equation

$$\frac{d}{dt}\left[u(t) - (\mathfrak{C}u)(t)\right] = (\mathfrak{Q}u)(t) \qquad \text{for a.e.} \quad t \in [0, a], \tag{4.1}$$

together the initial conditions  $u(0) = u_0$ , where  $\mathfrak{C}, \mathfrak{Q} : L^p([0, a], E) \to L^p([0, a], E)$  are continuous causal operators such that  $(\mathfrak{C}u)(0) = \theta$  for every  $u(\cdot) \in L^p([0, a], E)$ .

A function  $u(\cdot) \in L^p([0,a],E)$  is said to be a solution of (4.1) with initial condition  $u(0) = u_0$  if  $t \mapsto u(t) - (\mathfrak{C}u)(t)$  is an absolutely continuous function and satisfies (4.1) for a.e.  $t \in [0,a]$ . Note that  $u(\cdot)$  itself may not be differentiable on the interval of existence. It is easy to see that if  $u(\cdot)$  is a solution of equation (4.1), then it satisfies the integral equation

$$u(t) = (\mathfrak{P}u)(t) + \int_{0}^{t} (\mathfrak{Q}u)(s) ds \qquad \text{for a.e.} \quad t \in [0, a], \tag{4.2}$$

where  $(\mathfrak{P}u)(t) := u_0 + (\mathfrak{C}u)(t)$ ,  $t \in [0, a]$ . Conversely, if  $u(\cdot) \in L^p([0, a], E)$  satisfies the integral equation (4.2), then  $u(\cdot)$  is a solution of equation (4.1) with initial value  $u(0) = u_0$ . Let condition (H<sub>1</sub>) be satisfied and suppose that there exists  $k_1 \in [0, 1)$  and  $k_2 > 0$  such that  $\mathfrak{C}$  and  $\mathfrak{Q}$  satisfy (3.3).

Taking K(t,s)=I for all  $(t,s)\in\Delta:=\{(t,s);0\leq s\leq t\leq a\}$ , by Theorem 3.2 it follows that the integral equation (4.2) has at least one solution in  $L^p([0,a],E)$ . A similar result was obtained by Corduneanu [10] (Section 6.4) in the finite dimensional case. For instance, the above result can be applied to the neutral functional differential equation

$$\frac{d}{dt} \left[ u(t) - \int_{0}^{t} K(t,s)u(s)ds \right] = g(t,u(t)) \quad \text{for a.e.} \quad t \in [0,a],$$
 (4.3)

with the initial conditions  $u(0) = u_0$ , where  $K : \Delta \to \mathcal{L}(E)$  satisfies (H<sub>2</sub>) and  $g : [0, a] \times E \to E$  is a Carathéodory function; that is,

- (a)  $g(t, \cdot) \in C(E, E)$  for each  $t \in [0, a]$ ;
- (b)  $g(\cdot, u)$  is strongly measurable for each  $u \in E$ ;
- (c) There exist  $m_q(\cdot) \in L^p([0,a],\mathbb{R}_+)$  and  $d \geq 0$  such that

$$||g(t,u)|| \le m_g(t) + d||u||$$
 for every  $t \in [0,a]$  and  $u \in E$ .

Also, we assume that the following condition holds:

(H<sub>3</sub>) 
$$t \mapsto u(t) - \int_0^t K(t,s)u(s) \, ds$$
 is an absolutely continuous function on  $[0,a]$ .

Now, it is easy to see that if  $u(\cdot)$  is a solution of equation (4.3), then it satisfies the following integral equation:

$$u(t) = (\mathfrak{P}u)(t) + \int_{0}^{t} (\mathfrak{Q}u)(s) ds$$
 for a.e.  $t \in [0, a],$  (4.4)

where

$$(\mathfrak{P}u)(t) := u_0 + \int_0^t K(t, s)u(s)ds, \quad t \in [0, a],$$

is a Volterra operator and

$$(\mathfrak{Q}u)(t) := g(t, u(t)), \quad t \in [0, a],$$

is the Nemitskii operator. Conversely, if  $u(\cdot) \in L^p([0,a],E)$  satisfies the integral equation (4.4), then  $u(\cdot)$  is a solution of equation (4.3) with initial value  $u(0) = u_0$ .

**Theorem 4.1.** Suppose that  $K: \Delta \to \mathcal{L}(E)$  satisfies  $(H_2)$  and  $g(\cdot, \cdot): [0, a] \times E \to E$  is a Carathéodory function such that there exists  $k_2 > 0$  such that  $Ma^{1/p'+1/q'} + 2k_2a^{1/p-1/q}\|\xi\|_p < 1$  and

$$\alpha(g(t,A)) \le k_2 \alpha(A) \tag{4.5}$$

for  $t \in [0, a]$  and for each bounded subset  $A \subset E$ . If  $(H_3)$  hold, then the neutral functional differential equation (4.3) has at least one solution in  $L^p([0, a], E)$  satisfying the initial condition  $u(0) = u_0$ .

**Proof.** From (H<sub>2</sub>) and Theorem 9.5.1 in [15] it follows that  $\mathfrak{P}$  is a continuous operator from  $L^p([0,a],E)$  into itself. If V is a bounded countable set in  $L^p([0,a],E)$ , then we have

$$\alpha((\mathfrak{P}V)(t)) \leq \alpha \left( \int_0^t K(t,s)V(s)ds \right) \leq \int_0^t \alpha \left( K(t,s)V(s) \right) ds \leq$$

$$\leq \int_0^t \|K(t,s)\|\alpha \left( V(s) \right) ds \leq$$

$$\leq \left( \int_0^t \|K(t,s)\|^q ds \right)^{1/q} \left( \int_0^t \left[ \alpha \left( V(s) \right) \right]^{q'} ds \right)^{1/q'} \leq$$

$$\leq Ma^{1/q'-1/p} \left( \int_0^t \left[ \alpha \left( V(s) \right) \right]^p ds \right)^{1/p},$$

so that  $\mathfrak{P}$  satisfies (3.8). Also, by (c) it follows that the Nemitskii operator  $\mathfrak{Q}$  is a continuous operator from  $L^p([0,a],E)$  into itself. Next, using (4.5), for any bounded and countable set in  $L^p([0,a],E)$  we have  $\alpha\left((\mathfrak{Q}V)(t)\right)=\alpha\left(g(t,V(t))\right)\leq k_2\alpha\left(V(t)\right)$  for  $t\in[0,a]$ , so that  $\mathfrak{Q}$  also satisfies (3.3). Consequently, (H<sub>1</sub>), (H<sub>2</sub>) and (3.3) are satisfied so that, by Remark 3.2, the neutral functional differential equation (4.3) has at least one solution in  $L^p([0,a],E)$  satisfying the initial condition  $u(0)=u_0$ .

Theorem 4.1 is proved

- 5. A global existence result for nonlinear Fredholm functional integral equations. In this section we obtain a result on the global existence of solutions for a nonlinear Fredholm functional integral equation involving an abstract Volterra operator. A similar result was obtained by Warga [49] ([Theorem II.5.1]) in the finite dimensional case. If X, Y are given real separable Banach spaces, we denote by C(Y,X) the Banach space of all continuous and bounded functions from Y into X endowed with the norm  $\|f(\cdot)\|_{C(Y,X)} = \sup_{y \in Y} \|f(y)\|$ . We shall identify two functions  $g(\cdot,\cdot),h(\cdot,\cdot):[0,a]\times Y\to X$  if  $g(t,\cdot)=h(t,\cdot)$  a.e. on [0,a], and we will denote by  $\Omega:=\Omega([0,a]\times Y\times Y,X)$  the vector space of (equivalence classes of) all functions  $g(\cdot,\cdot):[0,a]\times Y\to X$  such that:
  - (c<sub>1</sub>)  $g(t, \cdot) \in C(Y, X)$  for each  $t \in [0, a]$ ;
  - (c<sub>2</sub>)  $g(\cdot, y)$  is strongly measurable for each  $y \in Y$ ;
  - (c<sub>3</sub>) there exists a function  $m_g(\cdot) \in L^p([0,a],\mathbb{R}_+)$  such that

$$||g(t,\cdot)||_{C(Y,X)} \le m_q(t)$$
 for every  $t \in [0,a]$ .

An element of  $\Omega$  is called a Carathéodory function.

**Remark 5.1.** It is easy to see that the function  $t \mapsto \|g(t,\cdot)\|_{C(Y,X)}$  is Lebesgue integrable on [0,a] for every  $g(\cdot,\cdot) \in \Omega$ . Moreover, the function  $g \mapsto \|g\|_{\Omega} \colon \Omega \to \mathbb{R}_+$ , given by

$$\|g\|_{\Omega} := \int_{0}^{a} \|g(t,\cdot)\|_{C(Y,X)} dt$$

is a norm on  $\Omega$ . Also, for every  $g(\cdot,\cdot)\in\Omega$  and for every strongly measurable functions  $y(\cdot)$ :  $[0,a]\to Y$ , the function  $t\mapsto g(t,y(t))$  is Bochner integrable on [0,a].

In the following, if  $F(\cdot) \in C([0, a], \Omega)$  is a given function, then we will write F(t, s, y) instead of F(t)(s, y) for  $(s, y) \in [0, a] \times Y$ .

Consider the nonlinear Fredholm functional-integral equation

$$u(t) = u_0(t) + \int_0^a F(t, s, (\mathfrak{Q}u)(s))ds, \quad t \in [0, a],$$
 (5.1)

where  $F(\cdot) \in C([0, a], \Omega)$ ,  $\mathfrak{Q} : C([0, a], X) \to L^{\infty}([0, a], Y)$ , and  $u_0(\cdot) \in C([0, a], X)$  are assumed to satisfy the following assumptions:

(A<sub>1</sub>)  $\mathfrak{Q}$ :  $C([0,a],X) \to L^{\infty}([0,a],Y)$  is continuous and there exists b>0 and 0< c<1 such that

$$\|\mathfrak{Q}u\|_{\infty} \le b(1 + \|u(\cdot)\|)^c, \quad u(\cdot) \in C([0, a], X);$$

(A<sub>2</sub>) there exist 0 < d < 1 and an integrable function  $h(\cdot, \cdot) : [0, a] \times [0, a] \to \mathbb{R}_+$  such that

$$\gamma := \sup_{0 \le t \le a} \int_{0}^{a} h(t, s) ds < \infty$$

and

$$\|F(t,s,y)\| \leq h(t,s)(1+\|y\|)^d \qquad \text{for} \quad t,s \in [0,a] \qquad \text{and} \qquad y \in Y;$$

(A<sub>3</sub>) there exist  $k, k_0 > 0$  and  $\psi(\cdot) \in L^1([0, a], \mathbb{R}_+)$  such that

$$\beta(F(t,s,B)) < k\beta(B)$$

for all  $t, s \in [0, a]$  and any bounded set  $B \subset Y$ , and

$$\beta((\mathfrak{Q}V)(t)) \le k_0 \beta(V(t))$$

for every  $t \in [0, a]$  and every bounded set  $V \subset C([0, a], X)$ .

**Theorem 5.1.** If assumptions  $(A_1)-(A_3)$  are satisfied,  $u_0(\cdot) \in C([0,a],X)$  and  $kk_0 < 1$ , then the integral equation (5.1) has at least one solution in C([0,a],X).

**Proof.** Since  $F(t,\cdot,\cdot)\in\Omega$  and the function  $s\mapsto (\mathfrak{Q}u)(s)$  is strongly measurable on [0,a] for each  $u(\cdot)\in C([0,a],X)$ , by Remark 5.1 it follows that the function  $s\mapsto F(t,s,(\mathfrak{Q}u)(s))$  is Bochner integrable on [0,a] for every  $t\in [0,a]$ , so that the operator

$$(Ku)(t) := u_0(t) + \int_0^a F(t, s, (\mathfrak{Q}u)(s))ds, \quad t \in [0, a],$$

is well defined for every  $u(\cdot) \in C([0,a],X)$ . Since 0 < c,d < 1, it is easy to check that, for a given  $\overline{r} \ge \max\{1,\gamma(1+2b)^c\}$ , we have  $\gamma \left[1+b(1+\overline{r})^d\right]^c \le \overline{r}_0$ . Let

$$W_r := \{ u(\cdot) \in C([0, a], X); ||u(\cdot)|| \le r \},$$

where  $r := \overline{r} + ||u_0(\cdot)||$ . First, we remark that, for every  $u(\cdot) \in W_r$ , we obtain

$$\|(\mathfrak{Q}u)(s)\| \le b(1 + \|u(s)\|)^c \le r_0 := b(1+r)^c$$

for a.e.  $s \in [0, a]$ , so that  $\mathfrak{Q}W_r \subset \{y(\cdot) \in L^{\infty}([0, a], Y); ||y(\cdot)|| \leq r_0\}$ . From (A<sub>1</sub>) and (A<sub>2</sub>) it follows that, for each  $u(\cdot) \in W_r$ , we get

$$||(Ku)(t)|| \le ||u_0(\cdot)|| + \int_0^a ||F(t, s, (\mathfrak{Q}u)(s))|| ds \le$$

$$\le ||u_0(\cdot)|| + \int_0^a h(t, s)(1 + ||(\mathfrak{Q}u)(s)||)^d ds \le$$

$$\le ||u_0(\cdot)|| + (1 + ||\mathfrak{Q}u||_{\infty})^d \sup_{0 \le t \le a} \int_0^a h(t, s) ds \le$$

$$\le ||u_0(\cdot)|| + \gamma \Big[ 1 + b(1 + \overline{r})^d \Big]^c \le ||u_0(\cdot)|| + \overline{r} = r,$$

so that  $Ku \in W_r$  for every  $u(\cdot) \in W_r$ . Since  $W_r$  is bounded and  $KW_r \subset W_r$ ,  $KW_r$  is also bounded. Now, we show that K is a continuous operator on  $W_r$ . For this, let  $\{u_n(\cdot)\}_{n\geq 1}$  be a sequence in  $W_r$  converging to some  $u(\cdot) \in W_r$ . Then by (A<sub>1</sub>) we have that  $\lim_{n\to\infty} (\mathfrak{Q}u_n)(s) = (\mathfrak{Q}u)(s)$  for a.e.  $s \in [0,a]$ . Also, since  $F(t,\cdot,\cdot) \in \Omega$ ,

$$\lim_{n \to \infty} F(t, s, (\mathfrak{Q}u_n)(s)) = F(t, s, (\mathfrak{Q}u)(s))$$

and

$$||F(t,s,(\mathfrak{Q}u_n)(s))|| \le \sup_{\|y\| \le r_0} ||F(t,s,y)|| \le (1+r_0)^d h(t,s)$$

for each  $t \in [0, a]$  and for a.e.  $s \in [0, a]$ , by the Lebesgue dominated convergence theorem we obtain

$$\lim_{n \to \infty} \int_{0}^{a} F(t, s, (\mathfrak{Q}u_n)(s)ds = \int_{0}^{a} F(t, s, (\mathfrak{Q}u)(s)ds$$

for each  $t \in [0, a]$ . Consequently, K is a continuous operator. Next, for every  $t, s \in [0, a]$  and every  $u(\cdot) \in W_r$ , we have

$$\begin{aligned} \big\| (Ku)(t) - (Ku)(s) \big\| &\leq \int_{0}^{a} \|F(t,\tau,(\mathfrak{Q}u)(\tau)) - F(s,\tau,(\mathfrak{Q}u)(\tau))\| d\tau \leq \\ &\leq \int_{0}^{a} \sup_{y \in Y} \big\| F(t,\tau,y) - F(s,\tau,y) \big\| d\tau = \\ &= \int_{0}^{a} \big\| F(t,\tau,\cdot) - F(s,\tau,\cdot) \big\|_{C(Y,X)} d\tau = \big\| F(t,\cdot,\cdot) - F(s,\cdot,\cdot) \big\|_{\Omega}. \end{aligned}$$

Since  $F(\cdot) \in C([0, a], \Omega)$ , for every  $\varepsilon > 0$ , there exists  $\delta = \delta(\varepsilon) > 0$  such that

$$||(Ku)(t) - (Ku)(s)|| \le ||F(t,\cdot,\cdot) - F(s,\cdot,\cdot)||_{\Omega} \le \varepsilon$$

for all  $t, s \in [0, a]$  with  $|t - s| \le \delta$  and for every  $u(\cdot) \in W_r$ , so that  $KW_r$  is equicontinuous. Next, put  $W_0 := W_r$  and define  $W_{n+1} = \overline{\operatorname{conv}}(KW_n), \ n = 0, 1, 2, \dots$ 

Now, from  $KW_0 \subset W_0$ , it follows that

$$W_1 = \overline{\operatorname{conv}}(KW_0) \subset \overline{\operatorname{conv}}(W_0) = W_0,$$

and thus,  $W_1 \subset C([0,a],X)$  is bounded, closed, convex and equicontinuous. By Mathematical induction it is easy to see that  $W_{n+1} \subset W_n$  and  $W_n \subset C([0,a],X)$  are bounded, closed, convex and equicontinuous for  $n=0,1,2,\ldots$  Next, since C([0,a],X) is separable, then for each  $n=0,1,2,\ldots$ , there exists a countable set  $V^n=\{v_k^n; k=1,2,\ldots\}\subset C([0,a],X)$  such that  $\overline{V^n}=W_n$ . Then, by Lemma 3.1, the properties of the measure of noncompactness and (A<sub>3</sub>), we have

$$\beta(W_{n+1}(t)) = \beta\left(\overline{\operatorname{conv}}((KW_n)(t))\right) = \beta\left((KW_n)(t)\right) = \beta\left((K\overline{V^n})(t)\right) \le$$

$$\le \beta\left(\int_0^a F(t,s,(\mathfrak{Q}\overline{V^n})(s))ds\right) \le$$

$$\le k\int_0^a \beta\left((\mathfrak{Q}\overline{V^n})(s)\right)ds \le kk_0\int_0^a \beta\left((\overline{V^n}(s))ds\right)$$

that is,

$$\beta(W_{n+1}(t)) \le kk_0 \int_0^a \beta(W_n(s)) ds, \quad t \in [0, b].$$

From a finite number of steps, we obtain

$$\beta(W_n(t)) \le (kk_0)^n \int_0^a \beta(W_0(s)) ds, \quad t \in [0, b], \quad n \ge 1.$$

From  $W_{n+1} \subset W_n$ ,  $n=0,1,2,\ldots$ , and property (4) of the measure of noncompactness, it follows that, for each  $t \in [0,b]$ , the sequence  $\{\beta(W_n(t))\}_{n\geq 0}$  is bounded and decreasing. Hence, there exists  $h(t) := \lim_{n\to\infty} \beta(W_n(t))$ ,  $t \in [0,b]$ . Taking  $n\to\infty$  on both sides of the last inequality we get

$$h(t) = \lim_{n \to \infty} \beta\left(W_n(t)\right) \le \lim_{n \to \infty} \left(kk_0\right)^n \int_0^a \beta\left(W_0(s)\right) ds = 0, \quad t \in [0, b],$$

and thus,  $h(t) = \lim_{n \to \infty} \beta\left(W_n(t)\right) = 0$ ,  $t \in [0, b]$ . Since  $W_n$ ,  $n = 0, 1, \ldots$ , are bounded and equicontiuous, it follows that  $\lim_{n \to \infty} \beta_c\left(W_n\right) = 0$ . By property (7) of the measure of noncompactness, it follows that  $W := \bigcap_{n=0}^{\infty} W_n$  is a compact set of C([0, a], X) and  $KW \subset W$ . Consequently, by the Schauder fixed point theorem, it follows that the operator K has at least one fixed point  $u(\cdot) \in W$ , which is a solution of (5.1).

## References

- 1. Agarwal R. P., Zhou Y., Wang J. R., Luo X. Fractional functional differential equations with causal operators in Banach spaces // Math. and Comput. Modelling. 2011. 54. P. 1440 1452.
- 2. Agarwal R. P., Arshad S., Lupulescu V., O'Regan D. Evolution equations with causal operators // Different. Equat. and Appl. 2015. 7, № 1. P. 15 26.
- 3. *Agarwal R. P., O'Regan D.* Infinite interval problems for differential, differential and integral equations. New York: Kluwer Acad. Publ., 2001.
- 4. Ahangar R. Nonanticipating dynamical model and optimal control // Appl. Math. Lett. 1989. 2. P. 15-18.
- 5. Akmerov R., Kamenskii M., Potapov A., Sadovskii B. Measures of noncompactness and condensing operators. Basel: Birkhäuser, 1992.
- Banaś J. Integrable solutions of Hammerstein and Urysohn integral equations // J. Austral. Math. Soc. Ser. A. 1989. –
   46. P. 61 68.
- 7. Barton T. A., Purnaras I. K. L<sup>p</sup>-solutions of singular integro-differential equations // J. Math. Anal. and Appl. 2012. **386**. P. 830 841.
- 8. Barton T. A., Zhang B. L<sup>p</sup>-solutions of fractional differential equations // Nonlinear Stud. 2012. 19. P. 161.
- 9. Bedivan D. M., O'Regan D. The set of solutions for abstract Volterra equations in  $L^p([0,a],R^m)$  // Appl. Math. Lett. -1999.-12.-P.7-11.
- 10. Corduneanu C. Functional equations with causal operators. London; New York: Taylor and Francis, 2002.
- 11. *Corduneanu C*. A modified LQ-optimal control problem for causal functional differential equations // Nonlinear Dyn. and Syst. Theory. 2004. 4. P. 139 144.
- 12. *Corduneanu C., Mahdavi M.* Neutral functional equations with causal operators on a semi-axis // Nonlinear Dyn. and Syst. Theory. 2008. **8**. P. 339 348.
- 13. Darwish M. A., El-Bary A. A. Existence of fractional integral equation with hysteresis // Appl. Math. and Comput. 2006. 176. P. 684–687.
- 14. *Drici Z., McRae F. A., Devi J. V.* Differential equations with causal operators in a Banach space // Nonlinear Anal.: Theory, Methods and Appl. 2005. **62**. P. 301–313.
- 15. Edwards R. E. Functional analysis theory and applications. New York: Holt, Rinehart and Winston, Inc., 1965.
- 16. *Emmanuele G*. About the existance of integrable solution of a functional-integral equation // Rev. Mat. Univ. Complut. Madrid. 1991. **4**, № 1.
- 17. *Gil' M. I.* Explicit stability conditions for neutral type vector functional differential equations. A survey // Surv. Math. and Appl. 2014. 9. P. 1 54.
- 18. Gil' M. I. Stability of neutral functional differential equations. Paris: Atlantis Press, 2014.
- 19. Gripenberg G., Londen S. O., Staffans O. Volterra integral and functional equations. Cambridge Univ. Press, 1990.
- 20. Guo D., Lakshmikantham V., Liu X. Nonlinear integral equations in abstract spaces. Dordrecht: Kluwer Acad. Publ., 1996
- 21. *Heinz H. P.* On the behaviour of measures of noncompactness with respect to differentiation and integration of vector valued-functions // Nonlinear Anal. 1983. 7. P. 1351–1371.
- 22. *Hernández E., Balachandran K.* Existance results for abstract degenrate neutral functional differential equations // Bull. Austral. Math. Soc. 2010. **81**. P. 329 342.
- 23. Hernández E., Perri M., Prokopczyk A., Hernández E., Pierri M., Prokopczyk A. On a class of abstract neutral functional differential equations // Nonlinear Anal. 2011. 74. P. 3633 3643.
- 24. *Hernández E., O'Regan D., Ben M. A.* On a new class of abstract integral equations and applications // Appl. Math. and Comput. 2012. 219, № 4. P. 2271 2277.
- 25. *Ilchmann A., Ryan E. P., Sangwin C. J.* Systems of controlled functional differential equations and adaptive tracking // SIAM J. Control and Optim. − 2002. − **40**, № 6. − P. 1746 − 1764.
- 26. *Isaia F.* On a nonlinear integral equation without compactness // Acta Math. Univ. Comenian. 2006. **75**, № 2. P. 233 240.
- 27. *Kamenskii M., Obukhovskii V., Zecca P.* Condensing multivalued maps and semilinear differential inclusions in Banach spaces. Berlin; New York: Walter de Gruyter, 2001.
- 28. *Kisielewicz M.* Multivalued differential equations in separable Banach spaces // J. Optim. Theory and Appl. 1982. 37, № 2. P. 231 249.

- 29. Kuratowski C. Sur les espaces complets // Fund. Math. 1930. 51. P. 301 309.
- 30. Kwapisz M. Remarks on the existance and uniqueness of solutions of volterra functional equations in  $L_p$  spaces // J. Integral Equat. and Appl. 1991. 3,  $\mathbb{N}_2$  3.
- 31. Kwapisz M. Bielecki's method, existence and uniqueness results for Volterra integral equations in  $L_p$  space // J. Math. Anal. and Appl. 1991. 154. P. 403–416.
- 32. *Lakshmikantham V., Leela S., Drici Z., McRae F. A.* Theory of causal differential equations // Atlantis Stud. Math. Eng. and Sci. 2010. Vol. 5.
- 33. Liang J., Yan S.-H., Agarwal R. P., Huang T.-W. Integral solution of a class of nonlinear integral equations // Appl. Math. and Comput. 2013. 219. P. 4950 4957.
- 34. Lupulescu V. Causal functional differential equations in Banach spaces // Nonlinear Anal. 2008. 69. P. 4787 4795.
- 35. *Lupulescu V.* On a class of functional differential equations in Banach spaces // Electron. J. Qual. Theory Different. Equat. 2010. **64**. P. 1–17.
- 36. *Mamrilla D.* On  $L^p$ -solutions of nth order nonlinear differential equations // Čas. pěstov. mat. 1988. 113. P. 363 368
- 37. *Martynyuk A. A., Martynyuk-Chernienko Yu. A.* Analysis of the set of trajectories of nonlinear dynamics: equations with causal robust operator // Different. Equat. 2015. 51, № 1. P. 11 22.
- 38. *Obukhovskii V., Zecca P.* On certain classes of functional inclusions with causal operators in Banach spaces // Nonlinear Anal.: Theory, Methods and Appl. 2011. **74.** P. 2765 2777.
- 39. Olszowy L. A family of measures of noncompactness in the space  $L^1_{loc}(R_+)$  and its application to some nonlinear Volterra integral equation // Mediterr. J. Math. 2014. 11. P. 687 701.
- 40. Prüss J. Evolutionary integral equations and applications. Basel: Birkhäuser, 1993.
- 41. *O'Regan D., Precup R.* Existence criteria for integral equations in Banach spaces // J. Inequal. and Appl. 2001. 6. P. 77 97.
- 42. *Ryan E. P., Sangwin C. J.* Controlled functional differential equations and adaptive tracking // Systems Control Lett. 2002. 47. P. 365 374.
- 43. Szufla S. Existence for  $L^p$ -solutions of integral equations in Banach spaces // Publ. Inst. Math. 1986. 54. P. 99 105.
- 44. *Szufla S.* Appendix to the paper An existence theorem for the Urysohn integral equation in Banach spaces // Comment. Math. Univ. Carolin. 1984. 25. P. 763 764.
- 45. Taggart R. J. Evolution equations and vector-valued  $L^p$  spaces: PhD thesis. New South Wales Univ., 2004.
- 46. *Tikhonov A. N.* Functional Volterra-type equations and their applications to certain problems of mathematical physics // Bull. Mosk. Gos. Univ. Sekt. A. − 1938. − 1, № 8. − P. 1 − 25.
- 47. Tonelli L. Sulle equazioni funzionali di Volterra // Bull. Calcutta Math. Soc. 1930. 20. P. 31 48.
- 48. Wang F. A fixed point theorem for nonautonomous type superposition operators and integrable solutions of a general nonlinear functional integral equation // J. Inequal. and Appl. 2014.
- 49. Warga J. Optimal control of differential and functional equations. New York: Acad. Press, 1972.
- 50. Zhu H. On a nonlinear integral equation with contractive perturbation / Adv. Difference Equat. 2011. 2011. Article ID 154742. 10 p., doi:10.1155/2011/154742.
- 51. Zhukovskii E. S., Alves M. J. Abstract Volterra operators // Russ. Math. 2008. 52. P. 1–14.

Received 26.11.17